# **Me scope**

# **VES-4600 Advanced Modal Analysis**

March 7, 2025



#### Notice

Information in this document is subject to change without notice and does not represent a commitment on the part of Vibrant Technology. Except as otherwise noted, names, companies, and data used in examples, sample outputs, or screen shots, are fictitious and are used solely to illustrate potential applications of the software.

#### Warranty

Vibrant Technology, Inc. warrants that (a) the software in this product will perform substantially in accordance with the accompanying documentation, for a period of one (1) year from the date of delivery, and that (b) any hardware accompanying the software will be free from defects in materials and workmanship for a period of one (1) year from the date of delivery. During this period, if a defect is reported to Vibrant Technology, replacement software or hardware will be provided to the customer at no cost, excluding delivery charges. Any replacement software will be warranted for the remainder of the original warranty period or thirty (30) days, whichever is longer.

This warranty shall not apply to defects resulting from improper or inadequate maintenance by the customer, customer supplied software or interfacing, unauthorized modification or misuse, operation outside of the environmental specifications for the product, or improper site preparation or maintenance.

If the software does not materially operate as warranted above, the sole remedy of the customer (and the entire liability of Vibrant Technology) shall be the correction or detour of programming errors attributable to Vibrant Technology. The software should not be relied on as the sole basis to solve a problem whose incorrect solution could result in injury to a person or property. If the software is employed in such a manner, it is at the entire risk of the customer, and Vibrant Technology disclaims all liability for such misuse.

NO OTHER WARRANTY IS EXPRESSED OR IMPLIED. VIBRANT TECHNOLOGY SPECIFICALLY MAKES NO WARRANTY OF ANY KIND WITH REGARD TO THIS MATERIAL, INCLUDING, BUT NOT LIMITED TO, THE IMPLIED WARRANTIES OF MERCHANT ABILITY AND FITNESS FOR A PARTICULAR PURPOSE.

THE REMEDIES PROVIDED HEREIN ARE THE CUSTOMER'S SOLE AND EXCLUSIVE REMEDIES. VIBRANT TECHNOLOGY SHALL NOT BE LIABLE FOR ANY DIRECT, INDIRECT, SPECIAL, INCIDENTAL, OR CONSEQUENTIAL DAMAGES IN CONNECTION WITH THE FURNISHING, PERFORMANCE, OR USE OF THIS PRODUCT, WHETHER BASED ON CONTRACT, TORT, OR ANY OTHER LEGAL THEORY.

The software described in this document is copyrighted by Vibrant Technology, Inc. or its suppliers and is protected by United States copyright laws and international treaty provisions. Unauthorized reproduction or distribution of this program, or any portion of it, may result in severe civil and criminal penalties, and will be prosecuted to the maximum extent possible under the law.

You may make copies of the software only for backup or archival purposes. No part of this manual may be reproduced or transmitted in any form or by any means for any purpose without the express written permission of Vibrant Technology.

Copyright © 1992-2024 by Vibrant Technology, Inc. All rights reserved. Printed in the United States of America.

#### Vibrant Technology, Inc.

13275 East Fremont Place Suite 270 Centennial, CO 80112 USA phone: (831) 430-9045 fax: (831) 430-9057 E-mail: support@vibetech.com http://www.vibetech.com

## **Table of Contents**

VES-4600 Advanced Modal Analysis	1
VES-4600 Advanced Modal Analysis	5
Additional Structure (STR) Commands	5
Additional Data Block (BLK) Commands	5
Multi-Reference Curve Fitting	5
Stability diagram	5
Additional Shape (SHP) Table Commands	5
Additional Shape (SHP) Table Columns	5
Special Mouse & Keyboard Commands	6
Stability diagram	6
When Is Multi-Reference Modal Testing Necessary?	6
Multi-Reference Modal Testing	6
Single-Reference FRFs	6
Multi-Reference FRFs	6
Multi-Reference Modal Testing	6
Multiple Shaker Test	7
Multi-Reference Roving Impact Test	7
Multi-Reference Mode Indicator	7
Multi-Reference CMIF	7
Multi-Reference MMIF	7
Modal Participation Factor	8
Multi-Reference Curve Fitting	8
Multi-Reference Polynomial	8
Stability Diagram Curve Fitting	8
Why Use a Stability diagram?	8
AF Polynomial (Alias-Free Polynomial)	8
Complex Exponential	8
Least Squares Complex Frequency (LSCF)	8
Creating a Stability diagram	8
What is a Stable Pole Group?	9
Stable Group Colors	9
Poles Diagram	10
Changing the Stable Groups Settings	10
Displaying Damping Values	10
Displaying Pole Values	10

Curve Fit   Stability   Clear Stability	11
Curve Fit   Stability   Stability Diagram (Stability button)	11
Curve Fit   Stability   Stability Reset (Reset button)	11
Curve Fit   Stability   Poles Selection Box	11
Curve Fit   Stability   Save Stable Groups (Save Groups button)	12
Display   Complexity Plot Data Block (BLK)	12
Normalized Mode Shape	12
Complex Mode Shape	12
Display   Complexity Plot Shape (SHP) Table	13
Normalized Shapes on the Complexity Plot	13
Normalization Line	14
Flipping the Phases of the Right-Hand Shape	14
Modal Phase Co-linearity (MPC)	14
Display   Magnitude Ranking Data Block (BLK)	14
Which Magnitudes Are Ranked?	15
Display the Magnitude Value	15
Display   Magnitude Ranking Shape (SHP) Table	15
Tools   Modal Decomposition	15
Tools   Modal Expansion	16
Display   M#s   Effective Mass, Stiffness, Damping	17
Tools   Modal Participation	17
Modal Participation Equation	17
Participation as a Least-Squared-Error Solution	18
Tools   Modal Expansion	18
Equation for the Expanded Shapes	19

#### **VES-4600 Advanced Modal Analysis**

If the **VES-4600 Advanced Modal Analysis** option is authorized by your MEscope license, the following commands are enabled in MEscope. Execute **Help** | **License Manager** to verify the Options authorized by your MEscope license.

#### Additional Structure (STR) Commands

- Animate | Normalize Shapes
- M# Links | Interpolate Source M#s

#### Additional Data Block (BLK) Commands

- Display | Complexity Plot
- Display | Magnitude Ranking
- Tools | Modal Decomposition
- Tools | Modal Expansion
- Curve Fit | **Stability** | **Stability** Clear
- Curve Fit | **Stability** | **Stability** diagram
- Curve Fit | **Stability** | **Stability** Reset
- Curve Fit | Stability | Poles Selection Box
- Curve Fit | Stability | Save Stable Groups

#### Multi-Reference Curve Fitting

• Multi-Reference curve fitting meth**ODS** are added on the Mode Indicator, Frequency Damping, & Residues Save Shapes tabs

#### Stability diagram

- The Stability diagram is enabled on the Mode Indicator display
- Stability tabs are added to the Frequency Damping tab
- The Stability tab contains several Multi-Reference curve fitting methODS
- The Stable Groups tab contains controls for defining stable groups of poles on the Stability diagram

#### Additional Shape (SHP) Table Commands

- Display | Complexity Plot
- Display | Magnitude Ranking
- Display | M#s | Effective Mass, Stiffness, Damping
- Display | Poles
- Tools | Modal Participation
- Tools | Modal Expansion

#### Additional Shape (SHP) Table Columns

- **MPC** (Modal Phase Co-linearity)
- Modal Participation

#### **Special Mouse & Keyboard Commands**

#### Stability diagram

- Click near a pole on the Stability diagram to display its Frequency & Damping
- Click near the Frequency & Damping of a pole to remove it from the Stability diagram
- Click on the Frequency & Damping and drag to move it on the Stability diagram
- *Hold down* the Ctrl Key and *click & drag* to draw a selection box enclosing a group of stable poles on the Stability diagram

#### When Is Multi-Reference Modal Testing Necessary?

Multi-Reference modal testing is required when a structure has resonances that occur under one of the following conditions,

- 1. Closely-coupled Modes: Resonance peaks *heavily overlapped* or *one resonance peak* for *two or more modes*.
- 2. **Repeated Roots**: Two or more modes have the *same natural frequency* but *different mode shapes*.
- 3. Local Modes: Modes have *non-zero mode shapes* only in *local regions* of a structure.

#### Multi-Reference Modal Testing

In a **Multi-Reference Modal Test**, multi-reference **FRFs** are calculated using data that is acquired using *two or more* **fixed Reference sensors**.

Multi-reference curve fitting is required to extract all modal parameters from a set of multi-reference FRFs.

#### Single-Reference FRFs

Single-reference **FRFs** are the *minimum requirement* for extracting modal parameters of a structure using **FRF**based curve fitting.

- Single-reference **FRFs** are obtained by exciting the structure with a *single fixed exciter* and *simultaneously acquiring* the force & response from *one or more response DOFs*
- Single-reference **FRFs** are also obtained by using a *single fixed response sensor* and *simultaneously acquiring* force & response while exciting the structure at *one or more excitation DOFs*

#### Multi-Reference FRFs

Multi-reference **FRFs** *are required* for extracting the modal parameters of **closely-coupled modes**, **repeated roots**, or **local modes** of a structure.

- Multi-reference **FRFs** are obtained by exciting the structure with *multiple fixed exciters* and *simultaneously acquiring* the forces & responses from *one or more response* **DOFs**
- Multi-reference **FRFs** are also obtained by exciting the structure at *multiple DOFs* and *simultaneously acquiring* the force and responses from *more than one response point* & *direction*.

#### **Multi-Reference Modal Testing**

A multi-reference modal test is done using either *multiple fixed exciters* with sensors to measure the forces, or *multiple fixed response* sensors.

A multi-reference modal test *is useful* when a structure has *high modal density* (many resonance peaks in close frequency to one another).

#### Multiple Shaker Test

Large structures will commonly exhibit *non-linear dynamic behavior*, so they are typically tested using multiple shakers, driven by *pure* or *burst* random excitation signals.

**Random excitation** together with **spectrum averaging** is used to *"average out"* the *non-linear dynamic behavior* of the structure from the spectra and hence from the **FRFs**.

- The multiple shakers must be driven with uncorrelated broad-band signals
- An **FRF** is calculated between *each force & each response*.
- Multiple & Partial Coherences are also calculated.

#### Multi-Reference Roving Impact Test

In this test, two or more fixed response sensors are used, and the structure is excited with a roving impactor.

- This test is the *same as performing* two or more Roving impact tests
- This test takes no more time to complete than a single-reference Roving impact test

#### **Multi-Reference Mode Indicator**

A Multi-Reference Mode Indicator is used for counting resonance peaks during Multi-reference curve fitting.

- A Multi-Reference Mode Indicator contains a separate curve for each reference
- A peak *at or near the same frequency in two or more* Multi-Reference Indicator curves indicates *closely-coupled modes* or *repeated roots*



Multi-Ref CMIFs Indicating Two Closely Coupled Modes Near 200 Hz.

#### Multi-Reference CMIF

A Multi-Reference CMIF is calculated by performing a *singular value decomposition* of multi-reference FRFs.

- A separate CMIF curve is calculated for each reference
- Each peak on a CMIF curve indicates a resonance

#### Multi-Reference MMIF

A **Multi-Reference MMIF** mode indicator is calculated by performing a *an eigen-solution* of multi-reference **FRFs**.

- A separate MMIF curve is calculated for each reference
- Each peak on an MMIF curve indicates a resonance

#### Modal Participation Factor

Each Multi-Reference **CMIF** & **MMIF** also provides a **Modal Participation Factor** curve for each multi-reference **FRF**.

Each Modal participation factor is used to weight each reference of FRF data during Multi-reference curve fitting

#### **Multi-Reference Curve Fitting**

MEscope contains several different Multi-Reference Parameter Estimation (curve fitting) methODS.

• Each curve fitting method uses a modal participation curve to weight the FRF data during curve fitting

#### Multi-Reference Polynomial

The Multi-Reference Polynomial method uses a multi-reference version of the **Rational Fraction Orthogonal Polynomial** method.

• The curve fitting model size in the **Modes** box on the **Polynomial** tab is used for estimating modal Frequency & Damping

#### **Stability Diagram Curve Fitting**

Why Use a Stability diagram?

A **Stability** diagram is a plot of pole estimates (**modal frequency & damping**) using a *progression* of curve fitting model sizes.

A **Stability** diagram *does not rely on peak counting* on a Mode Indicator curve.

- Stability curve fitting is done for model sizes from "1" to the Max. Model Size listed on the Stability tab
- Each modal frequency estimate is displayed as a vertical line on the Stability diagram
- Each modal damping estimate is displayed as a *horizontal line* on the Stability diagram
- The Stability tab contains several curve fitting methODS for estimating modal frequency & damping

#### AF Polynomial (Alias-Free Polynomial)

This method is an extension of the Rational Fraction Orthogonal Polynomial curve fitting method.

It is called *"alias-free"* because it places extra computational modes *toward the edges* of the *curve fitting band* instead of aliasing them throughout the band

Complex Exponential

This popular *time domain method* estimates poles by curve fitting **Impulse Response Functions (IRFs)**, the **Inverse FFT** of **FRFs**.

• During curve fitting, the Inverse FFT is applied to each FRF to obtain its corresponding IRF

Least Squares Complex Frequency (LSCF)

This method is an extension of the **Rational Fraction Orthogonal Polynomial** curve fitting method and uses the **Z**-transform to obtain more stable powers of the frequency variable.

The Z-transform maps frequencies to a unit circle, resulting in numerically stable solution equations.

Creating a Stability diagram

The Stability diagram is displayed on top of a Mode Indicator graph.

• Press the Stability button on the Stability tab or execute Curve Fit | Stability | Stability diagram

#### What is a Stable Pole Group?

Only Stable Pole Groups are displayed on the Stability diagram, unless Display All is checked.

A Stable Pole Group must meet all the following criteria listed on the Stable Groups tab

- All poles in a Stable Pole Group *must have* frequency estimates within the Frequency Tolerance
- All poles in a Stable Pole Group *must have* damping estimates within the Damping Tolerance
- A Stable Pole Group *must contain a* Min. Number of Stable Poles that satisfy the Frequency & Damping Tolerances

Stable Groups will change if the criteria for defining a Stable Group are changed.

• If the **Min. Number of Stable Poles** *is too small*, computational Poles will be displayed on the edges of the **Stability** diagram, as shown below



Computational Poles for Min. Number of Stable Poles → 4.

#### **Stable Group Colors**

All poles in a Stable Group are displayed using the same color on the Stability or Poles diagram



Stability diagram Showing Stable Pole Groups.

#### Poles Diagram

When the **Poles** box is *checked* on the Stable Groups tab, Poles estimates are displayed on a **Poles** diagram as shown below

- Modal frequency estimates are plotted along the *horizontal axis*
- Modal damping estimates are plotted along the *vertical axis*



Poles Diagram Showing Stable Groups

#### **Changing the Stable Groups Settings**

The **Stability** diagram is updated whenever the Frequency Tolerance, Damping Tolerance, or Min. Number of Stable Poles settings on the Stable Groups tab is changed.

To change the Frequency Tolerance, Damping Tolerance, or Min. Number of Stable Poles,

- Click on a radio button and scroll the slider on the right side
- Or type a number into the box next to the setting
- *Press* the **Reset** button to reset the **Stability** settings to default values

#### **Displaying Damping Values**

Damping values can be displayed on the **Stability** diagram either as a **percentage of critical damping** (%) or as the **3 dB** or **half power point damping** (in Hz).

• Select Damping (%) or Damping (Hz) on the Stable Groups tab to display damping in those units

#### **Displaying Pole Values**

To display a pole value on the Stability or Poles diagram

• Place the mouse pointer *near a pole* and *left click* near a pole to display its pole values

To remove the display of a pole value,

• Place the mouse pointer *on the pole value* and *left click* 



Pole Values Displayed on Poles Diagram

#### Curve Fit | Stability | Clear Stability

Clears the poles from the **Stability** diagram.

#### Curve Fit | Stability | Stability Diagram (Stability button)

Creates a Stability diagram by curve fitting all or selected M#s in a Data Block (BLK).

#### Curve Fit | Stability | Stability Reset (Reset button)

Resets the Stable Group parameters to default values.

#### Curve Fit | Stability | Poles Selection Box

Enables the Poles selection box on the Stability diagram.

When a Pole Selection box is drawn, the *average value* of the poles in the selection box is added to the **Modal Parameters** spreadsheet.

• Click & drag on the Stability or Poles diagram, to draw a selection box and enclose one or more poles



Pole Selection Box Drawn on the Stability Diagram.

#### Curve Fit | Stability | Save Stable Groups (Save Groups button)

When this command is executed (or the **Save Groups button is** *pressed*), the *average value of all poles* in each Stable Pole Group is added to the **Modal Parameters** spreadsheet.

• If the **Band** cursor is displayed, the *average value* of each Stable Pole Group *within the cursor band* is added to the **Modal Parameters** spreadsheet

#### Display / Complexity Plot Data Block (BLK)

Opens the Complexity Plot window from a Data Block (BLK) window.

A Complexity Plot displays the **magnitudes** & **phase** *all* (or *selected*) M# values at the *current Cursor position* 



Data Block (BLK) Complexity Plot.

#### Normalized Mode Shape

Each shape component of a **normalized mode shape** has a phase of **0** or **180 degrees**.

A normalized mode shape is also called a *normal mode shape*.

An FEA model with no damping yields normal mode shapes.

During shape animation, a normalized shape exhibits a standing wave motion, and its node lines do not move.

The shape components of a normalized shape *lie on a straight line* in a Complexity Plot.

#### **Complex Mode Shape**

Each shape component of a **complex shape** can have an **arbitrary phase**.

During shape animation, a complex shape can exhibit a *traveling wave* motion, and its node lines can move.

The shape components of a complex shape *do not lie on a straight line* in a Complexity Plot.

Experimental mode shapes can be *complex* for several reasons

- Real-world structures with *heavy damping* will have complex mode shapes
- Measurement errors can introduce arbitrary phase angles into EMA mode shape estimates
- Curve fitting errors can introduce arbitrary phases angles into EMA mode shape estimates

#### Display | Complexity Plot Shape (SHP) Table

Opens the Complexity Plot window from a Shape (SHP) Table window.

The Complexity Plot displays the magnitudes & phases for all (or selected) shapes for all (or selected) M#s



Shape (SHP) Table Complexity Plot.

Normalized Shapes on the Complexity Plot

When a complex shape is *normalized*, it behaves like a normal mode shape with real valued shape components.

When a complex shape is *normalized*, each shape component magnitude is retained, but its phase is changed to either **0** or **180** degrees

When **Display** | **Normalized Shape** is *checked*, *complex* shape components are displayed on the *left*, and *normalized* shape components are displayed on the *right* of the Complexity Plot, as shown below.



Complexity Plot with Display | Normalization Checked.

#### **Normalization Line**

When a shape is *normalized*, the **red** (+) shape components are given **0 degrees phase**, and the **blue** (-) shape components are given **180 degrees phase** 

The normalization line (dashed line) on a Complexity Plot is used to normalize each complex shape.

• Each shape in a Shape (SHP) Table can have a different normalization line

To rotate the normalization line to a different angle

• Click & drag near the normalization line on the Complexity Plot

#### Flipping the Phases of the Right-Hand Shape

During **Animate** | **Animate a Pair**, if two similar shapes are animating 180 degrees out of phase with one another, the phases of *right-hand* shape can be changed by 180 degrees so that the two shapes animate more closely together.

- Execute Animate | Animate a Pair | Flip Right Sign in the Structure (STR) window to multiply the *right-hand shape by ''-1''*
- Or *drag & rotate the the normalization line* on the Complexity Plot to flip the phase of the shape components

#### Modal Phase Co-linearity (MPC)

MPC is a measure of whether or not the components of a complex shape are normalized. they lie on a straight line.

**MPC** has values between 0 &1.

- If **MPC** =  $1 \rightarrow$  all components on the shape *lie on a straight line*
- If MPC < 1 → some shape components *do not lie on a straight line*
- If MPC is "close to  $1" \rightarrow$  the structure is lightly damped, or the shape is a normalized shape

#### Display | Magnitude Ranking Data Block (BLK)

Opens the Magnitude Ranking window from a Data Block (BLK) window.

- M# magnitudes are plotted on the *vertical axis* versus (DOFs or M#s) on the *horizontal axis*
- The magnitudes are ranked from the *largest on the left* to the *smallest on the right*
- The Contour Colors defined in the File | Data Block Options box are used for the Bar colors

M# magnitudes of the M#s at the current cursor position are displayed

- If *no cursors* are displayed, magnitudes of *all M#s* are displayed
- Magnitude Ranking is updated when the cursor is moved, or different M#s are selected



Data Block (**BLK**) Magnitude Ranking Chart.

#### Which Magnitudes Are Ranked?

- If the **Real** part of the **M#s** is displayed, the **Real** parts are ranked
- If the Imaginary part of the M#s is displayed, the Imaginary parts are ranked
- Otherwise, the Magnitudes of the M#s are ranked

#### **Display the Magnitude Value**

• Hover the mouse pointer over a magnitude bar to display its value at the bottom of the window

#### Display | Magnitude Ranking Shape (SHP) Table

Displays the magnitudes of the M#s for *all* (or *selected*) shapes and *all* (or *selected*) M#s in a Shape (SHP) Table.

• Magnitude Ranking is updated when different shapes are selected, or different M#s are selected

#### Tools / Modal Decomposition

Decomposes time or frequency M#s in a Data Block (BLK) into "resonance curves" that represent the contribution of each mode shape at each sample of M# data.

This command uses the same equations as the **Tools** | **Modal Participation** command in a **Shape** (**SHP**) **Table** but *applies them at each sample* of **M**# data.

Only mode shapes are used for decomposition. Modal frequency & damping are not used.

The following equation is solved at *each sample of time or frequency* data in the Data Block (BLK)

[Shapes] {Decomp(sample)} = {ODS(sample)}

(n by m) (m by 1) (n by 1)

[Shapes] → matrix of mode shapes (n by m). Each column of [Shapes] contains a mode shape

 $\{Decomp(sample)\} \rightarrow$  participation of each mode shape in the  $\{ODS\}$  at each sample

**{ODS(sample)}** → **ODS** data *at each sample* in the Data Block (**BLK**)

- $n \rightarrow$  number of mode shape **DOFs**
- $\mathbf{m} \rightarrow$  number of mode shapes

The mode shapes in [Shapes] must meet the following conditions,

- The mode shapes are valid for the structure *regardless of boundary conditions*
- The mode shapes *must have* **DOFs** *that match* those of the Data Block (**BLK**)
- The mode shapes must be *linearly independent* of one another for the *matching* **DOFs**
- *Linear independence* of the mode shapes in [Shapes] can be validated by displaying their MAC values when the *matching* DOFs *are selected*



Modal Decomposition into Ten Resonance Curves.

Each resonance curve *can be curve fit to extract the experimental modal frequency & damping* associated with that resonance.

#### Tools / Modal Expansion

Expands the time or frequency M#s in a Data Block (BLK) using mode shapes.

Only mode shapes are used for Modal Expansion. Frequency & damping are not used.

This command uses the same equations as the **Tools** | **Modal Expansion** command in a **Shape** (**SHP**) **Table** but *applies them at each sample* of **M**# data,

The mode shapes must meet the following conditions,

- The mode shapes are valid for the structure *regardless of boundary conditions*
- The mode shapes *must have* **DOFs** *that match* those of the Data Block (**BLK**)
- The mode shapes must be *linearly independent* of one another at the *matching* **DOFs**
- *Linear independence* of the mode shapes in [Shapes] can be validated by displaying their MAC values when the *matching* DOFs *are selected*

Modal Expansion can be controlled by *selecting* shapes in the Shape (SHP) Table and/or *selecting* M#s in the Data Block (BLK)

The expanded M#s can be curve fit using any FRF-based curve fitting method.

#### Display | M#s | Effective Mass, Stiffness, Damping

Displays the effective mass, stiffness & damping (also called **generalized mass, stiffness & damping**) of each mode shape in the **M#s** spreadsheet.

Effective mass, stiffness & damping are the values each mode would have if it were a single Mass-Spring-Damper located at a **DOF** of the mode shape.

This command can only be used with UMM mode shapes

Effective mass, damping & stiffness are calculated for each mode with the formulas

Effective Mass = 1 / (Freq x Real (DP Residue) + Damp x Imaginary (DP Residue) Effective Stiffness = (Freq<sup>2</sup> + Damp<sup>2</sup>) x Effective Mass Effective Damping = 2 x Damp x Effective Mass

**Freq**  $\rightarrow$  damped natural frequency of the mode

**Damp**  $\rightarrow$  half power point damping of the mode

**DP Residue** → *driving point Residue* for each component of the mode shape

#### **Tools / Modal Participation**

Calculates the Modal Participation, the *numerical participation* of one set of shapes in another set of shapes.

The Modal Participation equates the shapes in one **Shape (SHP) Table** with the shapes of another **Shape (SHP) Table** 

Each Shape (SHP) Table can contain ODS's, EMA mode shapes, OMA mode shapes, FEA mode shapes or Engineering Data Shapes

#### **Modal Participation Equation**

If two sets of shapes are assembled into two matrices **[U] & [V]**, where *each column* of each matrix contains a shape, the two shape matrices are equated to each other with the following equation involving a Modal Participation.

[U] [Part] = [V]

 $[U] \rightarrow$  matrix of complex shapes (**m** by **n**)

 $[V] \rightarrow$  matrix of complex shapes (**m by q**)

[Part]  $\rightarrow$  complex Modal Participation (**n** by **q**)

- $\mathbf{n} =$ number of shapes in [U]
- **q** = number of shapes in **[V]**
- **m** = number of matching DOFs between **[U] & [V]**

Writing out the matrices in terms of their components

$$\begin{bmatrix} u_{1,1} & \cdots & u_{1,n} \\ \vdots & \ddots & \vdots \\ u_{m,1} & \cdots & u_{m,n} \end{bmatrix} \begin{bmatrix} p_{1,1} & \cdots & p_{1,q} \\ \vdots & \ddots & \vdots \\ p_{n,1} & \cdots & p_{n,q} \end{bmatrix} = \begin{bmatrix} v_{1,1} & \cdots & v_{1,q} \\ \vdots & \ddots & \vdots \\ v_{m,1} & \cdots & v_{m,q} \end{bmatrix}$$
  
(m by n) (n by q) (m by q)

#### Participation as a Least-Squared-Error Solution

The Modal Participation is a *least-squared-error solution* to the above equation using the formula,

## $[Part] = \left[ [U]^{h}[U] \right]^{-1} [U]^{h}[V]$

#### **h** → denotes the *transposed conjugate matrix*

- -1  $\rightarrow$  denotes the *inverse matrix*
- The shapes [U] must be valid for the structure *regardless of boundary conditions*.
- Only the shapes in **[U]** are required for the Modal Participation calculation. Modal frequency & damping *are not used*.
- The shapes in [U] & [V] must have *some matching* **DOFs**
- The shapes in [U] must be *linearly independent* of one another for the *matching* DOFs between the shapes in [U] & [V]
- *Linear independence* of the shapes in **[U]** can be validated by displaying their **MAC values** for the *matching* **DOFs**

#### Tools | Modal Expansion

Expands the number of DOFs in a **Shape (SHP) Table** using shapes *with more* **DOFs** from another **Shape (SHP) Table**.

- Modal Expansion calculates a Modal Participation as described under Tools | Modal Participation
- The Modal Participation is multiplied by the shapes with many M#s to obtain the expanded shapes
- Any valid shapes for the structure can be used for Modal Expansion, regardless of their boundary conditions
- Only mode shapes are used for Modal Expansion. Frequency & Damping are not required
- The frequency & damping of each un-expanded shape are retained with each expanded shape



#### **Equation for the Expanded Shapes**

The matrix of expanded shapes  $[V_e]$  is calculated with the following equation,

$$[V_{e}] = \begin{bmatrix} V_{m} \\ V_{u} \end{bmatrix} = \begin{bmatrix} U_{m} \\ U_{u} \end{bmatrix} [Part]$$

[U<sub>m</sub>], [V<sub>m</sub>] → sub-matrices with *matching* DOFs
[U<sub>u</sub>], [V<sub>u</sub>] → sub-matrices with *un-matched* DOFs
[Part] → Modal Participation

Modal Expansion can be controlled by *selecting shapes* and/or *selecting* M#s in either Shape (SHP) Table